

Whatever Happened to Pump Stroke Optimization?

Bill Elmer, P.E. ALRDC Artificial Lift Workshop February 28th – March 3rd, 2022

History of Pump Stroke Optimization

- Concept and data from two pilot wells first presented to industry at ALRDC Sucker Rod Pumping Workshop in September 2015
- Case Study of 20 Well Eagle Ford pilot presented at Southwestern Petroleum Short Course in April 2016, and in peer reviewed SPE Paper 181228-PA
- Four well Bakken pilot presented in September 2016 at ALRDC Sucker Rod Pumping Workshop





What is Pump Stroke Optimization?

- Part 1: For wells with excess pump capacity, preferentially slowing pumping speed on downstroke
 - Results in less slippage and better pump fillage
 - Referred to as <u>Slow Downstroke Mode</u> or SDSM
- Part 2: Address the problem of wave and slug flow in horizontal wells that mislead RPC's into cycling between max and min speeds
 - Results in poor pump fillage and rod buckling
 - Requires setting max pumping speed near average



PSO Part 1: "Slow Downstroke Mode" Two ways to run at 3 SPM

- Old School Method for 3 SPM
 - Total stroke duration is 20 seconds
 - Upstroke duration is 10 seconds, as is downstroke
- Slow Downstroke Mode (SDSM)
 - ▶ 6 SPM on upstroke, a 5 second duration
 - 2 SPM on downstroke, a 15 second duration
 - Total stroke duration still 20 seconds but upstroke duration only <u>25%</u> of each stroke, not 50% (5/20 instead of 10/20)

SDSM Example: Pumping at 3 SPM





2015 Sucker Rod Pumping Workshop

Use of the Pump Slippage Equation to Design Pump Clearances (Rowlan, McCoy, Lea)

Pump Slippage

1) Fluid that leaks back into pump between the Plunger OD and the Barrel ID

 Leaks into the pump chamber between the standing valve and traveling valve
When traveling ball is on Seat.

Pump Efficiency = BPD Tank / BPD Pump

Slippage % = Slippage BPD / BPD Pump

ept. 25 - 28, 2012

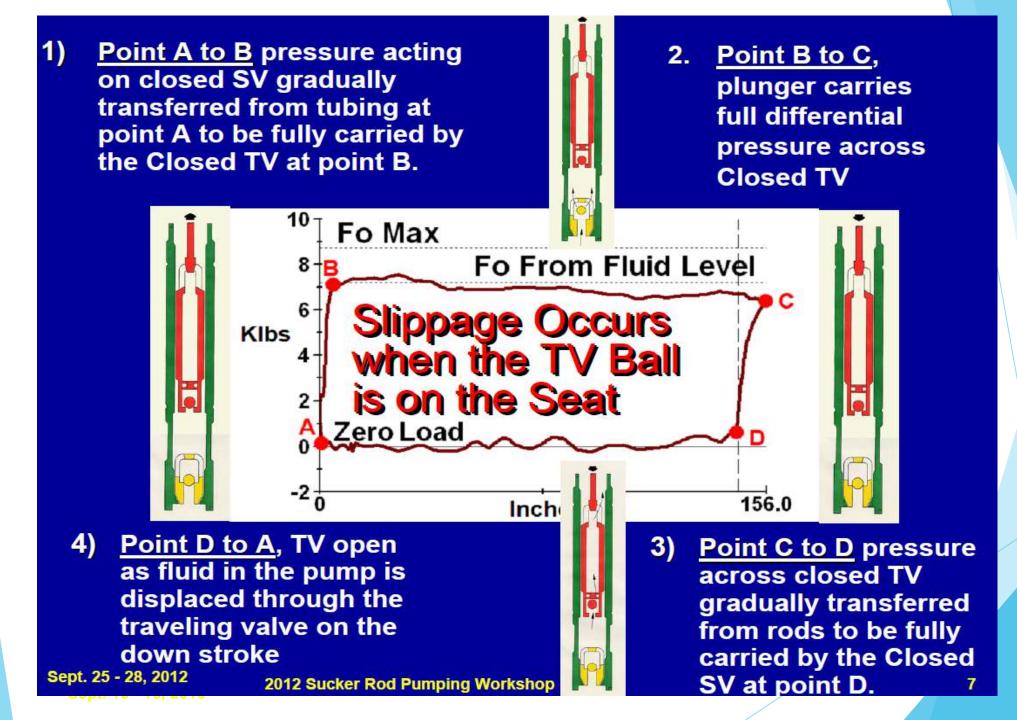
2012 Sucker Rod Pumping Workshop



- Slippage

BPD Tank = BPD Pump

01/14/2022



Observations about Pump Slippage

- Pump Slippage during the Upstroke reduces system efficiency
 - Since standing valve is open, slippage replaces fluid that would normally enter pump
 - Less Time on Upstroke = Less pump slippage
- Pump slippage during the Downstroke does not impact system efficiency, but improves fillage
 - Since standing valve closed during downstroke, new well fluids not entering the pump anyway
 - Slippage fluids fill pump, opening travelling valve sooner
 - Pump fillage increased, reduced rod buckling

8

Artificial Li

R&D Counc

From SPE 181228: Pump Slippage Equation Correction



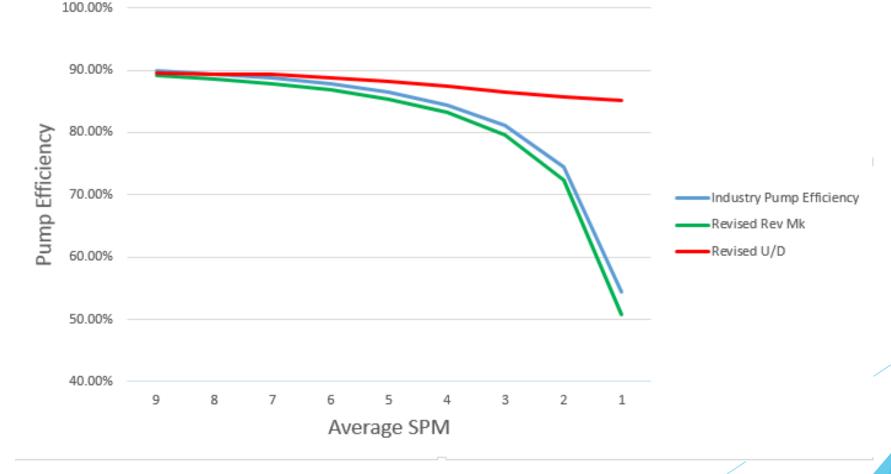
- 2001 Thesis by Chambliss submitted to Texas Tech: "Plunger Leakage and Viscous Drag for Beam Pump Systems"
 - Pump slippage greater for alternative geometry pumping units that had unequal upstroke and downstroke travel time

$$B_{Adjusted} = \frac{Degrees_{UP}}{180} B_{Calculated}$$

However, Chambliss did not consider variation in pumping speed induced travel time differences. A revised equation that considers both is presented:

Patterson slippage formula modified for % Upstroke Duration

Pump Efficiency Using Arco-HF-COP Base, Reverse Mark, U/D Speed Control 1.5" Pump at 10000 Feet with .006 clearance, 0.7 vis 350 psi PIP, 6 foot plunger, 0.8 gravity fluid 4 SPM Max SPM Differential, 4 sec Accel/Decel



Artificial Lift R&D Council

PSO Part Two: Setting Pumping Speeds

Artificial Lift R&D Council



2015 Sucker Rod Pumping Workshop

The result: Poor pump fillage.

Sept. 15 -16, 2015



How do operators address poor pump fillage due to horizontal well slugging?

- By manually setting pumping speed
 - Limiting maximum pumping speed
 - Reducing the minimum pumping speed
- The current approach requires
 - Regular monitoring by personnel
 - Resetting pumping speeds as wells continue to deplete
- PSO Part 2 is autonomous setting of these speeds

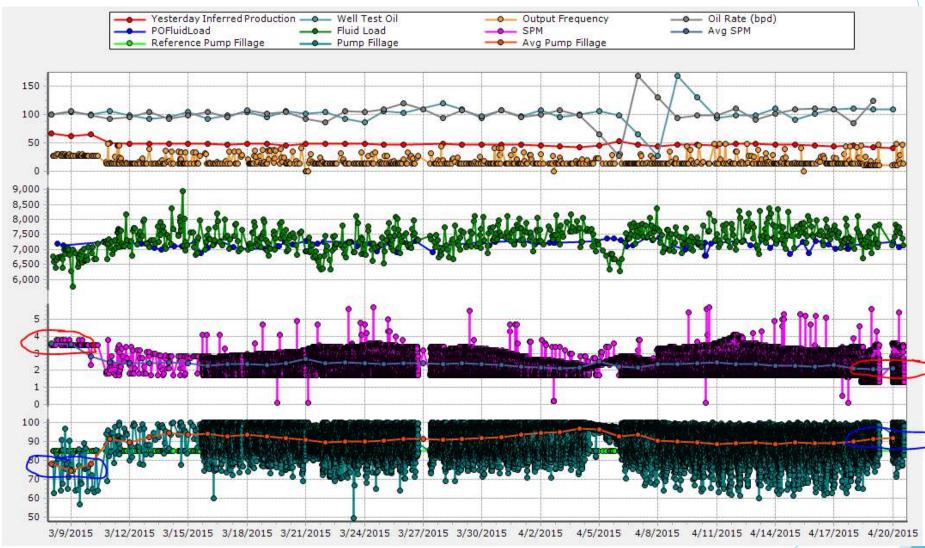


SDSM (PSO Part 1) decreases slippage and increases pump fillage, increasing efficiency

- Also more time for evolving gas to exit gas anchor
 - Less gas enters pump, more liquid
- Higher minimum rod loads due to slow downstroke/ less gas
 - Reduces buckling tendencies
 - Allows higher maximum rod loads
- Has nothing to do with setting pumping speeds
 - That is PSO Part 2

Well #1: 35% reduction in strokes per day, oil production not significantly affected





2015 Sucker Rod Pumping Workshop

Se 1

Well #1: Minimum load increased by 1000 pounds, maximum load same





Sept. 15 -16,2015



Why PSO Part 2 works

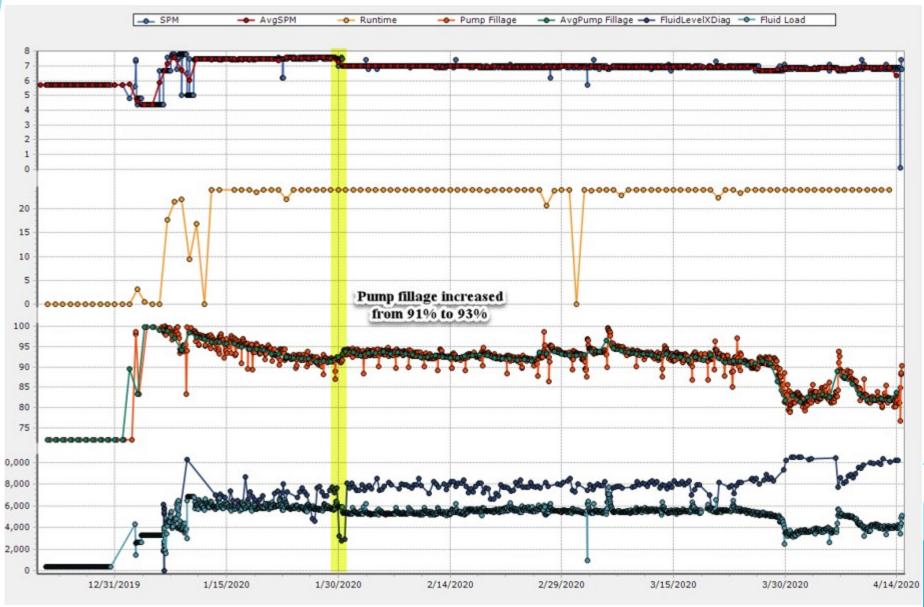
PSO Part 2 does what you would do, create maximum working speed setpoints that are better aligned with the average production rate

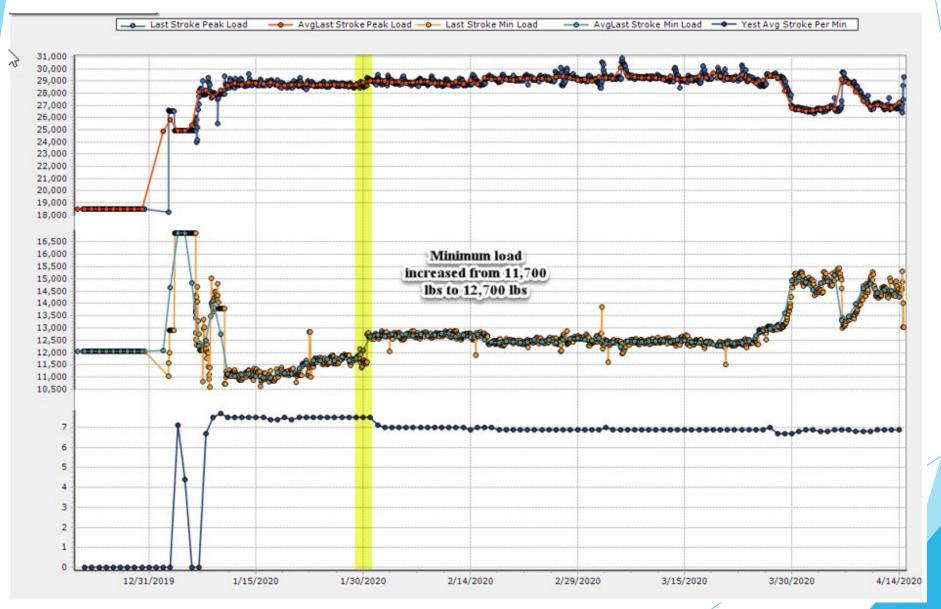
- This prevents over-reacting to high pump fillages often seen at the beginning of a slug event
- Keeping the maximum pumping speed slightly higher than average pumping speed helps avoid low pump fillage events and rod buckling

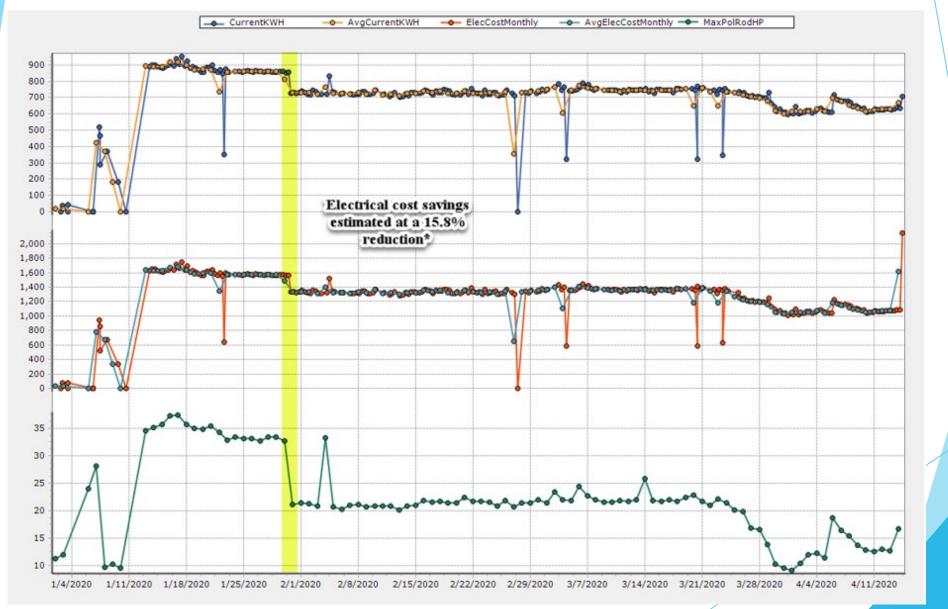
Some operators are using SDSM today

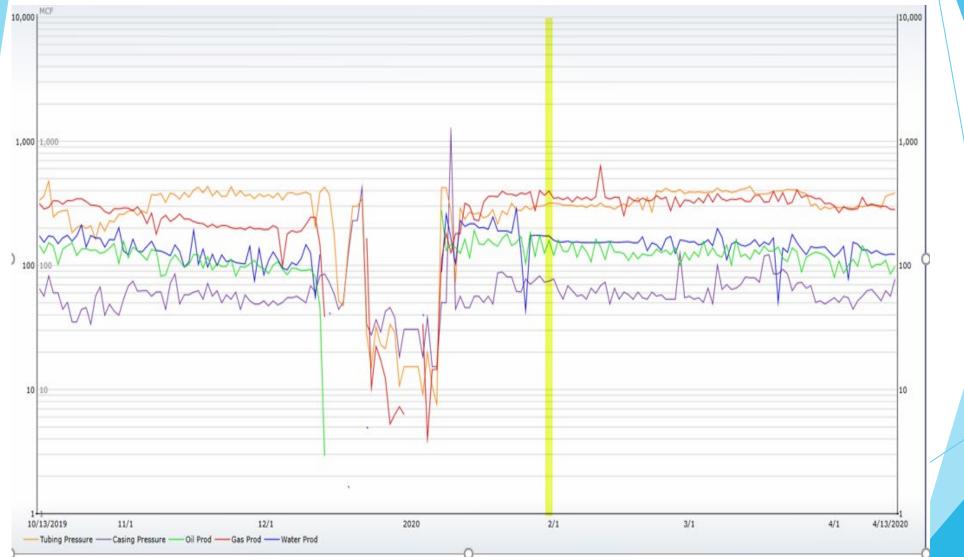
- Continental Resources using SDSM in Bakken
 - No hardware modifications needed
 - Using Scada to load SDSM settings into RPC's
- Operator in Eagle Ford using SDSM on 400+ wells
 - Working towards applying PSO Part 2 via Data Analytics











- SDSM / PSO doesn't increase production
 - Makes same production with less strokes (less wear)
 - Lower power consumption documented
 - Neither were home run reasons
- Could not prove that less strokes and higher minimum rod loads would result in less failures
 - No long-term failure studies performed
- Pumps with leaking standing valves lost production
 - 5% of pilot test wells saw this



- Is major change in operation
 - Simulation programs can't handle it
 - Unrealized fears about equipment failures
 - Required PLC to be inserted in RPC cabinet
- RPC companies felt threatened
 - Wasn't invented by them
 - Hardware could not perform PSO Part 2
 - Encline had applied for a patent
 - Result: Warranty voided if operator tried
- Oil price dropped and spending stopped



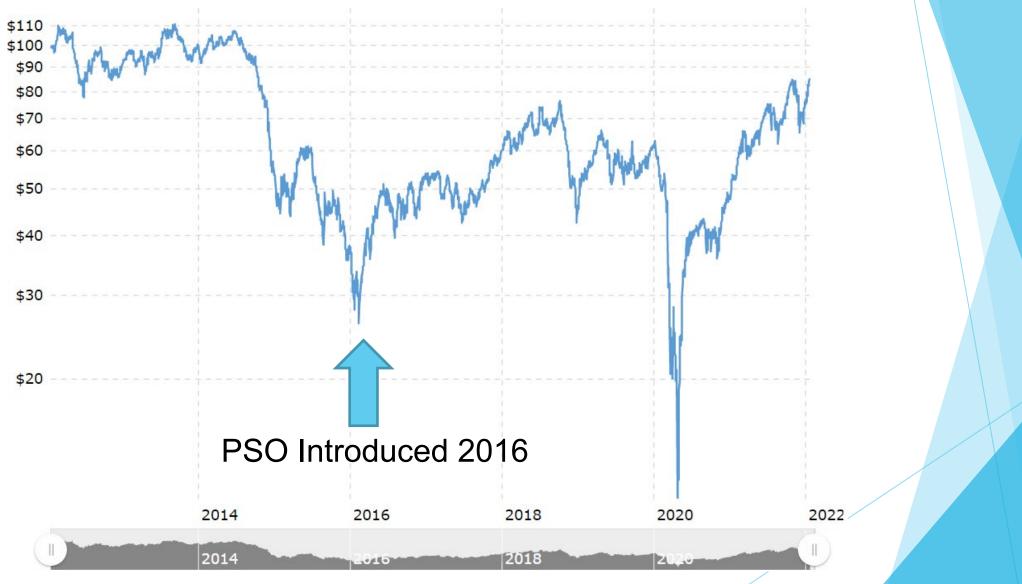


23

Artificial I

R&D Counc







- Gas Lift became popular for horizontals
 - Less industry interest in rod pumping
 - Introduction of HPGL in 2016 shifted Encline resources from PSO due to idea importance
- Slow Downstroke Mode and PSO are not plug and play
 - SDSM requires routine parameter review
 - PSO sets all parameters, but requires periodic algorithm evaluation
 - Neither simple enough for busy operator personnel
 - Opportunities for Machine Learning?



The Future?

- Encline dropped all patent efforts years ago when it became clear that adoption would be difficult
- RPC manufacturers are free to incorporate PSO
- Operators are free to incorporate PSO into Data Analytics / Machine Learning efforts
 - Let the cloud tell the RPC upstroke and downstroke pumping speeds
- Encline has free guide to SDSM setup. Visit enclinelift.com and request in contact section



Acknowledgements/Thanks & Questions

Thanks to Lynn Rowlan, Jim Lea, and Jim McCoy for allowing use of their 2012 Pump Slippage slides in this presentation

Special thanks to Mike Blake of Continental Resources for providing detailed data on their SDSM trials

Thanks to all operators who performed trials of PSO and opted to support Encline's R&D efforts by purchasing PSO hardware



Copyright

Rights to this presentation are owned by the company(ies) and/or author(s) listed on the title page. By submitting this presentation to the Gas-Lift Workshop, they grant to the Workshop, the Artificial Lift Research and Development Council (ALRDC) rights to:

- Display the presentation at the Workshop.
- Place it on the <u>www.alrdc.com</u> website, with access to the site to be as directed by the Workshop Steering Committee.
- Links to presentations on ALRDC's social media accounts.
- Place it on a USB/CD for distribution and/or sale as directed by the Workshop Steering Committee.

Other uses of this presentation are prohibited without the expressed written permission of the company(ies) and/or author(s) who own it and the Workshop Steering Committee.



Disclaimer

The Artificial Lift Research and Development Council and its officers and trustees, and the Artificial Lift Workshop Steering Committee members, and their supporting organizations and companies (here-in-after referred to as the Sponsoring Organizations), and the author(s) of this Technical Presentation or Artificial Lift Learning Course and their company(ies), provide this presentation and/or training material at the Artificial Lift Workshop "as is" without any warranty of any kind, express or implied, as to the accuracy of the information or the products or services referred to by any presenter (in so far as such warranties may be excluded under any relevant law) and these members and their companies will not be liable for unlawful actions and any losses or damage that may result from use of any presentation as a consequence of any inaccuracies in, or any omission from, the information which therein may be contained.

The views, opinions, and conclusions expressed in these presentations and/or training materials are those of the author and not necessarily those of the Sponsoring Organizations. The author is solely responsible for the content of the materials.

The Sponsoring Organizations cannot and do not warrant the accuracy of these documents beyond the source documents, although we do make every attempt to work from authoritative sources. The Sponsoring Organizations provide these presentations and/or training materials as a service. The Sponsoring Organizations make no representations or warranties, express or implied, with respect to the presentations and/or training materials, or any part thereof, including any warrantees of title, non-infringement of copyright or patent rights of others, merchantability, or fitness or suitability for any purpose.